Package vignette for TBFmultinomial

Dynamic cause-specific variable selection for discrete time-to-event competing risks models

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1 Introduction

This vignette shall serve as an introduction to the R-package TBFmultinomial, written for the implementation of the methods presented in Heyard et al. [2018]. The package glmBfp does objective Bayesian variable selection using a methodology based on test-based Bayes factors (TBF) for generalised linear models [Held et al., 2015] as well as for the Cox model [Held et al., 2016]. However, glmBfp cannot handle multinomial outcomes. Therefore, the package TBFmultinomial is an extension that allows for mulitple outcomes as in the multinomial regression model. Most importantly the package has been developped for discrete time-to-event models with competing risks. The TBF methodology can easily be extended to these models, which are simple multinomial regression models with a time-dependent intercept, see Heyard et al. [2018].

2 Data example

Our data example will be similar to the one presented in Heyard et al. [2018], but simplified. The goal of the analysis is to find a prediction model for the risk of acquiring a ventilator-associated pneumonia (VAP). However if a patient is extubated or dies, a VAP cannot be diagnosed anymore. Extubation and death then compose the competing events/risks for VAP acquisition. The data is stored in the package as VAP_data.

```
library('TBFmultinomial')
```

```
## Loading required package: VGAM
## Loading required package: stats4
## Loading required package: splines
## Loading required package: nnet
## Loading required package: parallel
## Loading required package: stringr
```

Loading required package: plotrix

data("VAP_data")
dim(VAP_data)

[1] 1640 7

head(VAP_data, 10)

## 1 2 1 0 Medical 50 9 ventilated ## 2 2 2 0 Medical 50 8 ventilated ## 3 2 3 0 Medical 50 9 ventilated	outcome
	ventilated
## 3 2 3 0 Medical 50 9 ventilated	ventilated
	ventilated
## 4 2 4 0 Medical 50 9 ventilated	ventilated
## 5 2 5 0 Medical 50 8 VAP	VAP
## 6 3 1 1 Medical 34 10 ventilated	ventilated
## 9 3 4 1 Medical 34 6 ventilated	ventilated
## 10 3 5 1 Medical 34 5 ventilated	ventilated
## 12 3 7 1 Medical 34 2 ventilated	ventilated
## 13 3 8 1 Medical 34 1 ventilated	ventilated
<pre>table(VAP_data\$outcome)</pre>	
##	
## ventilated dead extubated VAP	
## 1530 20 80 10	

Each row in the data set stands for one day of ventilation of a patient as it is needed for discrete survival models. If the data is in a short format, functions like discSurv::dataLong(). We have 1640 ventilation days for 90 distinct patients. We now want to find a prediction model for the variable outcome by selecting among the baseline variable gender, type (patient type, can be medical or surgical) and SAPSadmission (the simplified acute physiology score at admission) as well as the time-dependent variable SOFA (the daily sequential organ failure assessment score).

3 Dynamic Bayesian variable selection

We will now proceed step by step to dynamic Bayesian variable selection in order to define a prediction model for the time to acquire a VAP taking into account its competing risks.

3.1 Posterior model probability

The first step will be to fit the candidate models and compute their posterior probabilities using the function PMP(). Our methodology is based on the *g*-prior so that we need to decide on a way to define g. We can either simply set g equal to the sample size with method='g=n', or use an empirical Bayes (EB) approach like the local EB with method='LEB' or the global EB with method='GEB'. An other possibility is a fully Bayes approach with method \in {'ZS', 'ZSadapted', 'hyperG', 'hyperGN'}. We refer to Held et al. [2015] for further detail on the definition of g.

To use the PMP() function we first need to define the full model containing all the potential predictors with a time-dependent intercept. Here we define natural spline with 4 degrees on the variable day for the intercept:

```
full <- outcome ~ ns(day, df = 4) +
gender + type + SAPSadmission + SOFA
class(full)</pre>
```

```
## [1] "formula"
```

The formula can be defined as a formula-class or as a character. Then we can apply the function on our data and use the default settings for the other parameters. By default a LEB approach is used for the estimation of g, a uniform (flat) prior is used on the candidate model space, the nnet package is used to fit the models with 150 iterations (max). We further need to tell the function that we are considering a discrete survival model by setting discreteSurv to TRUE, so that the function knows that ns(day, df = 4) is interpreted as the intercept.

Then, using the generic function as.data.frame(), we can nicely represent an object of class PMP; the models are ordered by their posterior probability. So the first element in the data frame is the model with the highest PMP: the maximum a posteriori (MAP) model is the candidate with only SOFA as predictor.

```
class(PMP_LEB_flat)
## [1] "PMP"
              "list"
as.data.frame(PMP_LEB_flat)
                                      type SAPSadmission
##
         posterior logPrior gender
                                                           SOFA
      5.328383e-01 -2.772589
##
                               FALSE FALSE
                                                    FALSE
                                                           TRUE
  5
## 10 3.572925e-01 -2.772589
                               FALSE
                                      TRUE
                                                    FALSE
                                                           TRUE
## 15 3.607272e-02 -2.772589
                               FALSE
                                      TRUE
                                                     TRUE
                                                           TRUE
## 11 2.774031e-02 -2.772589
                               FALSE FALSE
                                                     TRUE
                                                           TRUE
## 13 2.427082e-02 -2.772589
                                TRUE
                                      TRUE
                                                    FALSE
                                                           TRUE
## 8 1.671044e-02 -2.772589
                                TRUE FALSE
                                                    FALSE
                                                           TRUE
## 16 3.392558e-03 -2.772589
                                TRUE
                                     TRUE
                                                     TRUE
                                                           TRUE
```

## 14	1.682432e-03 -2.772589	TRUE FALSE	TRUE TRUE
## 9	3.331786e-15 -2.772589	FALSE TRUE	TRUE FALSE
## 4	3.038039e-15 -2.772589	FALSE FALSE	TRUE FALSE
## 12	2.025561e-15 -2.772589	TRUE TRUE	TRUE FALSE
## 7	1.566718e-15 -2.772589	TRUE FALSE	TRUE FALSE
## 3	2.615036e-16 -2.772589	FALSE TRUE	FALSE FALSE
## 6	2.593422e-16 -2.772589	TRUE TRUE	FALSE FALSE
## 2	1.677275e-16 -2.772589	TRUE FALSE	FALSE FALSE
## 1	1.590463e-16 -2.772589	FALSE FALSE	FALSE FALSE

Instead of defining a full model as an input for the function, we can also fix the formulas of all the candidate models we want to consider before and store them in a character vector with the first element being the reference model and the last the most complex model. Then we set the parameter candidateModels to this vector and leave fullModel undefined. In this way, we can fix some variables to be included by default, or simply use and fit only a sample of all possible candidate models if the model space is big.

3.2 Posterior inclusion probability

Using the PMP-object, the posterior inclusion probabilities (PIPs) can be computed with the postInclusionProb() function.

postInclusionProb(PMP_LEB_flat)

 ##
 gender
 type
 SAPSadmission
 SOFA

 ##
 0.04605625
 0.42102855
 0.06888802
 1.00000000

So a median probability model (MPM) would only include the variable SOFA as its PIP is higher (or equal) to 0.5.

3.3 Cause-specific variable selection

The PIPs refer to the importance of a variable as a predictor for all outcomes together. We may want to quantify the relevance of a variable for the prediction of each outcome individually. Therefore we proceed to cause-specific variable selection CSVS as described in Heyard et al. [2018]. The function CSVS() can be applied on one particular model either fitted using multinom() of the package nnet or using vglm() from VGAM. Note that we need a fixed g, so we cannot use the fully Bayes methods for CSVS:

The function plot_CSVS then plots the results and prints the coefficients before and after CSVS:

```
## $before
##
        gender1 typeSurgical SAPSadmission
                                                 SOFA
## 1 0.7360920
                 -0.7644011
                                1.2416076 2.8581988
## 2 -0.9435592
                  -2.4763176
                                -0.7786595 -6.5665457
## 3 -0.6957668
                  -0.9161588
                                -0.7380157 0.5375009
##
## $after
##
    gender1 typeSurgical SAPSadmission
                                             SOFA
## 1
           0
                 0.000000
                                      0 3.759587
                -2.288231
                                      0 -6.686574
## 2
           0
## 3
           0
                 0.000000
                                      0 0.000000
```

The color scale in Figure 1 is defined with white to red corresponding to 0.538 to 6.567 for the upper plot and to 0 to 6.687 for the lower plot. Furthermore, the outcomes are defined as 1:dead, 2:extubated and 3:VAP.

3.4 Dynamic variable selection using landmarking

In a very last step, we can proceed to dynamic variable selection via landmarking using the function PIPs_by_landmarking(). The landmarking technique has been extensively discussed by van Houwelingen [2007], used in connection with PIPs by Held et al. [2016] and been extended to the context of discrete time-to-event competing risks model by Heyard et al. [2018]. To do so, we need to set the same parameters as for PMP(). Further, we need to specify the landmark length in days (here landmarkLength=4), the last landmark (here lastlandmark=20) and the name of the variable indication the time (here timeVariableName = 'day').



Before CSVS

Figure 1: Absolute values of the shrunken standardized coefficients before and after CSVS.

See Figure 2 for the evolution of the PIPs over time. If again, we only include the variable with PIP ≥ 0.5 for the MPM, we would use a different set of predictors depending on the landmark considered or the time already spent at risk.

4 (Simple) multinomial regression

We can as well apply the TBF methodology on multinomial regression models by setting the parameter discreteSurv to FALSE.

References

- L. Held, D. Sabanés Bové, and I. Gravestock. Approximate Bayesian model selection with the deviance statistic. *Statistical Science*, 30(2):242–257, 05 2015. doi: 10.1214/14-STS510.
- L. Held, I. Gravestock, and D. Sabanés Bové. Objective Bayesian model selection for Cox regression. *Statistics in Medicine*, page 5376–5390, 2016. doi: 10.1002/sim.7089. sim.7089.
- R. Heyard, J.-F. Timsit, W. I. Essaied, and L. Held. Dynamic clinical prediction models for discrete time-to-event data with competing risks - a case study on the outcomerea database. *Biometrical Journal*, 2018. doi: 10.1002/bimj.201700259.
- H. C. van Houwelingen. Dynamic prediction by landmarking in event history analysis. Scandinavian Journal of Statistics, 34:70–85, 2007.



Figure 2: The posterior inclusion probabilities for each landmark.