Package 'CircOutlier'

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Description

The data used in here, obtained by using Monte-Carlo simulation method.

Usage

data("DMCE")

Details

A simulation study is carried out to find the percentile (cut-off) point of DMCE by using Monte-Carlo methods. Fifteen different sample sizes are used, namely $n = 10, \ldots, 150$. For each sample size n, a set of random circular errors is generated from the von Mises distribution with mean direction 0 and various values of concentration parameter $k = 1, 2, \ldots, 100$. Samples of von Mises distribution $VM(\pi/4, 10)$ with corresponding size n are generated to represent the values of X variable. The parameters of model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,...,n) are fixed at α =0 and β =1. Observed values of the response variable y are calculated based on model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,...,n) and subsequently the fitted values Y are obtained. We then compute the value of the MCE statistic for full data set. Sequentially, we exclude the ith observation from the generated sample, where i = 1, ..., n. We refit the reduced data using model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,...,n) and then calculate the values of MCe. Then, we obtain the value of DMCE. The process is carried out 2000 times for each combination of sample size n and concentration parameter k.

References

A. H. Abuzaid, A. G. Hussin & I. B. Mohamed (2013) Detecting of outliers in simple circular regression models using the mean circular error statistics.

DMCEE

Detection of Outliers in Circular-Circular Regression

Description

This function calculates the absolute values of the difference between the values of MCE and MCe statistic. Then, it draws the scatter plot of them and estimates the concentration parameter of k. Given the sample size and the estimated value of K, cut-off point from the table DMCE in the significance level of 0.05 or 0.1 will be found. Outliers are located on the top of teh line corresponding to the cut-off point.

Usage

DMCEE(x, y, b)

Huberized

Arguments

х	independent variable on model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,,n)
У	the response variable on model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,,n)
b	the level of significance (0.05 or 0.1)

Details

The ith observation is identified as an outlier if the absolute values of the difference between the values of MCE and MCe statistic exceeds a pre-specified cut-off point.

Author(s)

Azade Ghazanfarihesari, Majid Sarmad

References

A. H. Abuzaid, A. G. Hussin & I. B. Mohamed (2013) Detection of outliers in simple circular regression models using the mean circular error statistics

See Also

circular, CircStats

Examples

data(wind2)
DMCEE(wind2[,1], wind2[,2], .9)

Huberized

Detecting Outliers in Circular Data and Modifying Its

Description

This function is used to identify outliers in circular data sets. and with do the procedure Huberized on this outliers, the results improve. Huberizing the outliers will improve the results. circular and sd.circular are mean and standard deviation of circular data.

Usage

Huberized(t)

Arguments

t

circular data set which contains suspected outliers.

Details

In this method, we progressively transform the original data by a process called winsorisation. Assume that we have initial estimates called m,s. (These coulde evaluated as mean and standard deviation.) If a value x_i falls above m+(1.5*s) then we change it to $x_i = m + (1.5 * s)$. Likewise if a value falls below m-(1.5*s) then we change it to $x_i = m = (1.5 * s)$. We then calculate an improved estimate of mean as m1=mean.circular(x_i), and of the standard deviation as s1=1.134*(sd.circular(x_i)).(The factor 1.134 is derived from the normal distribution, given a value 1.5 for the multiplier most often used in the winsorisation process.) (see the first reference)

Value

Two plot and four number

a list containing the following values:

plot1	plot data set when exist outlier.
plot2	plot data set after modified outlier.
m	mean.circular when exist outlier.
m1	mean.circular after modified outlier.
S	sd.circular when exist outlier.
s1	sd.circular after modified outlier.

Author(s)

Azade Ghazanfarihesari, Majid Sarmad

References

Analytical Methods Committe, Robust statistics: a method coping with outliers, Royal Society of Chemistry 2001, amc technical brief.

A. H. Abuzaid, A. G. Hussin & I. B. Mohamed (2013) Detecting of outliers in simple circular regression models using the mean circular error statistics.

See Also

circular, CircStats

Examples

data(wind) Huberized(wind) MCE

Description

Mean circular error

Usage

MCE(y, Y, n)

Arguments

У	observed values of the response variable are calculated based on model
	$y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,,n). here n is sample size. random error
	having a VonMises distribution with circular mean 0 and concentration
	parameter k.
Υ	the estimated value of y under model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,,n).
n	the sample size

Details

This function may be considered as a type of arithmetic mean which is not robust to the existence of outlier.thus it can be used to detect the possible outliers in the circular regression.

Value

Number, that is mean circular error.

Author(s)

Azade Ghazanfarihesari, Majid Sarmad

References

A. H. Abuzaid, A. G. Hussin & I. B. Mohamed (2013) Detection of outliers in simple circular regression models using the mean circular error statistics.

See Also

circular, CircStats

Examples

```
#Generate a data set dependent of circular variables.
library(CircStats)
n <- 50
x <- rvm(n = 50, 0, 2)
y <- rvm(n = 50, pi/4, 5)
# Fit a circular-circular regression model.
circ.lm <- circ.reg(x, y, order = 1)
Y <- circ.lm$fitted
MCE(y, Y, n)
```

MCe

Detection of Outliers in Circular-circular Regression

Description

Removal of the ith observation from the data set calculate mean circular error for reduced data set

Usage

MCe(u)

Arguments

u

cosine the difference between the observed value of the response variable y and fitted values Y on model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,...,n).

Details

This function after removal of the ith observation from the data set.

Value

Number, that is mean circular error after removal of the ith observation from the data set.

Author(s)

Azade Ghazanfarihesari, Majid Sarmad

References

A. H. Abuzaid, A. G. Hussin & I. B. Mohamed (2013) Detection of outliers in simple circular regression models using the mean circular error statistics

See Also

circular, CircStats

Predict

Examples

```
# Generate a data set dependent of circular variables.
library(CircStats)
  x <- rvm(n = 50, 0, 2)
y <- rvm(n = 50, pi/4, 5)
# Fit a circular-circular regression model.
circ.lm <- circ.reg(x, y, order = 1)
Y <- circ.lm$fitted
MCe(cos(y - Y))
```

Predict

Estimates of Parameters in Circular-Circular Regression

Description

This function calculated the maximum-likelihood estimates parameters

Usage

Predict(x, y)

Arguments

Х	independent variable on model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,,n)
У	the response variable on model $y_i = \alpha + \beta x_i + \epsilon_i \pmod{2\pi}$ (i=1,2,,n)

Details

This function uses of iterative methods for the parameter estimates in circular-circular regression model and The user can default values The desired change.

Value

Number

a list containing the following values:

alpha1	estimate of α
beta1	estimate of β

Author(s)

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Azade Ghazanfarihesari, Majid Sarmad

References

A. H. Abuzaid, A. G. Hussin & I. B. Mohamed (2013) Detection of outliers in simple circular regression models using the mean circular error statistics

wind2

See Also

circular,CircStats

Examples

Generate a data set dependent of circular variables. library(CircStats) x <- rvm(n = 50, 0, 2) y <- rvm(n = 50, pi/4, 5) Predict(x, y)

wind

Wind Direction

Description

The data used in here, obtained after doing some calculations on the data to be recorded of Holderness coastline(the Humberside coast of the North sea, UK).

Usage

data("wind")

References

A. H. Abuzaid, A. G. Hussin & I. B. Mohamed (2013) Detection of outliers in simple circular regression models using the mean circular error statistics.

wind2

Wind Direction

Description

The data used in here, recorded over a period of 22.7 days along the Holderness coastline(the Humberside coast of the North sea, UK) by using two different instruments: a high frequency (HF) radar system and an anchored wave buoy.

Usage

data("wind2")

References

A. H. Abuzaid, A. G. Hussin & I. B. Mohamed (2013) Detecting of outliers in simple circular regression models using the mean circular error statistics.

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