

# Package ‘QLearning’

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**Type** Package  
**Title** Reinforcement Learning using the Q Learning Algorithm  
**Version** 0.1.1  
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**Description** Implements Q-Learning, a model-free form of reinforcement learning, described in work by Strehl, Li, Wiewiora, Langford & Littman (2006) <doi:10.1145/1143844.1143955>.  
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qlearn	<i>qlearn</i>
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## Description

Input a *game* that has variables *statevars* (which the player can keep track of). The player can perform any of *possibleactions*. The output matrix will give the expected value of each action (column) in each state (row).

**Usage**

```
qlearn(game, statevars, possibleactions, playername="P1",
       numiter=1000, prevstrategy=NULL, ...)
```

**Arguments**

<code>game</code>	Name of the game to be played/learned.
<code>statevars</code>	A vector of the states to be monitored inside <i>game</i> . These are the conditions under which the player has to make his decision.
<code>possibleactions</code>	A vector of the names of the possible actions inside <i>game</i> . This should be a list of every possible action that can be taken, regardless of state.
<code>playername</code>	The name of the variable that holds the name for the player's action inside <i>game</i> . See <b>Details</b> .
<code>numiter</code>	Number of iterations of <i>game</i> . Defaults to 50.
<code>prevstrategy</code>	Reward matrix returned by a previous <i>qlearn</i> function; serves as a starting point. Defaults to a blank reward matrix.
<code>...</code>	Additional arguments to be passed to <i>game</i> .

**Details**

At some point in game, there must be a line of the format

```
playername <- 'Choose'
```

where `playername` is substituted with the parameter "playername". This line should be at the point where the user wants to have the player choose an action. Since `playername` defaults to "P1", it is sufficient to put the line:

```
P1 <- 'Choose'
```

somewhere in the function.

**Value**

A matrix describing the expected reward values of performing a certain action (columns) in a certain state (rows).

**Note**

Contact at [liam.bressler@yale.edu](mailto:liam.bressler@yale.edu)

**Author(s)**

Liam Bressler

**References**

<http://labressler.github.io/analytics>

**Examples**

```

cardgame <- function()
{
  playercards <- sample(1:8,4) #distribute the cards, we're player one
  ourcard <- playercards[1] #our card
  playertotals <- rep(-1,4) #including the antes
  playersinpot <- vector()
  for (player in 2:4) #other 3 players go first
  {
    if (playercards[player]>=2)
    {
      playertotals[player] <- (-3)
      playersinpot <- append(playersinpot,player)
    }
  }
  #the next line is where we want to choose our action
  player1 <- 'Choose'
  if (player1=="Call")
  {
    playertotals[1] <- (-3)
    playersinpot <- append(playersinpot,1)
  }
  potsize <- -1*(sum(playertotals)) #the amount in the pot is how much the players put in
  playercards[!(1:4 %in% playersinpot)] <- 0 #get rid of everyone who folded
  winner <- which.max(playercards) #winner is the person with the highest card who didn't fold
  playertotals[winner] <- playertotals[winner]+potsize
  return(playertotals[1]) #return how much we won
}

strat <- qlearn(game="cardgame",statevars="ourcard",possibleactions=c("Call","Fold"),
  playername="player1",numiter=25000) #make sure each function and variable name is a string

strat

```

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qlearningaction

qlearningaction

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**Description**

This repository implements **Q-Learning**, a model-free form of reinforcement learning in R.

**Usage**

```
qlearningaction(q, currentstate, exploration=.5)
```

**Arguments**

<code>q</code>	Input state/action matrix.
<code>currentstate</code>	Current state of the game. Does not have to match any of the state for $q$ .
<code>exploration</code>	The probability of choosing a random state, rather than the one with the highest EV. Default 0.5.

**Details**

For internal use for *qlearn*.

**Value**

An action to take, taken from the possible actions of  $q$ .

**Note**

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**Author(s)**

Liam Bressler

**References**

<http://labressler.github.io/analytics>

**Examples**

```
cardgame <- function()
{
  playercards <- sample(1:8,4) #distribute the cards, we're player one
  ourcard <- playercards[1] #our card
  playertotals <- rep(-1,4) #including the antes
  playersinpot <- vector()
  for (player in 2:4) #other 3 players go first
  {
    if (playercards[player]>=2)
    {
      playertotals[player] <- (-3)
      playersinpot <- append(playersinpot,player)
    }
  }
  #the next line is where we want to choose our action
  player1 <- 'Choose'
  if (player1=="Call")
  {
    playertotals[1] <- (-3)
    playersinpot <- append(playersinpot,1)
  }
  potsize <- -1*(sum(playertotals)) #the amount in the pot is how much the players put in
  playercards[!(1:4 %in% playersinpot)] <- 0 #get rid of everyone who folded
```

```

    winner <- which.max(playercards) #winner is the person with the highest card who didn't fold
    playertotals[winner] <- playertotals[winner]+potsize
    return(playertotals[1]) #return how much we won
}

strat <- qllearn(game="cardgame",statevars="ourcard",possibleactions=c("Call","Fold"),
  playername="player1",numiter=25000) #make sure each function and variable name is a string

qllearningaction(strat,3,exploration=.75)
#Pick an action to perform when we have the 3 card, with high exploration

```

qllearningupdate

*qllearningupdate***Description**

This repository implements **Q-Learning**, a model-free form of reinforcement learning in R.

**Usage**

```
qllearningupdate(q, currentstate, currentaction, currentreward, nextstate=NULL,
  rewardcount=.5, gamma=.25)
```

**Arguments**

q	Input state/action matrix.
currentstate	Current state of the game. Does not have to match any of the state for <i>q</i> .
currentaction	Action to take.
currentreward	Reward for <i>currentaction</i> in current iteration.
nextstate	State that the game is in after taking <i>currentaction</i> .
rewardcount	Regularization constant for reward.
gamma	Learning rate constant for Q-Learning.

**Details**

For internal use for *qllearn*.

**Value**

An updated state/action matrix.

**Note**

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**Author(s)**

Liam Bressler

## References

<http://labressler.github.io/analytics>

## Examples

```
cardgame <- function()
{
  playercards <- sample(1:8,4) #distribute the cards, we're player one
  ourcard <- playercards[1] #our card
  playertotals <- rep(-1,4) #including the antes
  playersinpot <- vector()
  for (player in 2:4) #other 3 players go first
  {
    if (playercards[player]>=2)
    {
      playertotals[player] <- (-3)
      playersinpot <- append(playersinpot,player)
    }
  }
  #the next line is where we want to choose our action
  player1 <- 'Choose'
  if (player1=="Call")
  {
    playertotals[1] <- (-3)
    playersinpot <- append(playersinpot,1)
  }
  potsize <- -1*(sum(playertotals)) #the amount in the pot is how much the players put in
  playercards[!(1:4 %in% playersinpot)] <- 0 #get rid of everyone who folded
  winner <- which.max(playercards) #winner is the person with the highest card who didn't fold
  playertotals[winner] <- playertotals[winner]+potsize
  return(playertotals[1]) #return how much we won
}

strat <- qlearn(game="cardgame",statevars="ourcard",possibleactions=c("Call","Fold"),
  playername="player1",numiter=25000) #make sure each function and variable name is a string

strat <- qlearningupdate(strat,currentstate=7,currentaction="Call",currentreward=5)
#Update the matrix after an example when we call with the 7 card as our state, winning 5 chips
```

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